

A theorem of H. Hopf and the Cauchy-Riemann inequality II

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Abstract. This is a sequel to “A theorem of H. Hopf and the Cauchy-Riemann inequality” [AdCT]. Here the result of the previous paper is extended (see the precise statement in Section 1 of the present paper) to surfaces in three-dimensional homogeneous Riemannian manifolds whose group of isometries has dimension four and the bundle curvature is nonzero, whereas in the previous paper only the case of vanishing bundle curvature was treated.

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1 Introduction

Let \mathbb{E}^3 be a 3-dimensional simply-connected homogeneous riemannian manifold with a 4-dimensional isometry group. Such a manifold is a riemannian fibration with bundle curvature τ over a 2-dimensional space form with sectional curvature k . They are classified, up to isometries, by k and τ , where k and τ are any two real numbers with $k \neq 4\tau^2$ and $k^2 + \tau^2 \neq 0$. We will denote them by $\mathbb{E}^3(k, \tau)$. When $\tau = 0$ (hence $k \neq 0$), we have the spaces $M^2(k) \times \mathbb{R}$. When $\tau \neq 0$, we have the Berger spheres, for $k > 0$, the Heisenberg 3-space, for $k = 0$, and the universal covering of the Lie group $SL_2(\mathbb{R})$, for $k < 0$. The fibers of $\mathbb{E}^3(k, \tau)$ are geodesics (straight lines in the case $\tau = 0$) the translations along which generate a Killing vector field ξ . The bundle curvature τ is given by $\bar{\nabla}_X \xi = \tau \xi \times X$, where $\bar{\nabla}$ is the covariant derivative, X is any vector

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field, and \times is the cross product in $\mathbb{E}^3(k, \tau)$. We refer to [D] for further details on these spaces and their immersed surfaces.

For the case $\tau = 0$, Abresch and Rosenberg [AR1] considered a surface M immersed in $M^2(k) \times \mathbb{R}$ and introduced a quadratic form on M by

$$Q(X, Y) = 2H\alpha(X, Y) - k\langle \xi, X \rangle \langle \xi, Y \rangle,$$

where X and Y are tangent vectors, α is the second fundamental form and H is the mean curvature of M . Introduce in M isothermal parameters (u, v) (this means that the induced metric on M is $ds^2 = \lambda^2(du^2 + dv^2)$) and let $z = u + iv$ be the corresponding complex parameter.

Abresch and Rosenberg proved the $(2, 0)$ -component $Q^{(2,0)}$ of Q is holomorphic if $H = \text{const}$. This generalizes a previous result of H. Hopf [H] for the case where M is immersed in \mathbb{R}^3 . Furthermore, they showed that if M is homeomorphic to a sphere, then M is an embedded surface invariant by rotations of $M^2(k) \times \mathbb{R}$ around the factor \mathbb{R} .

Alencar, do Carmo and Tribuzy [AdCT] showed that it is not necessary to assume that $H = \text{const}$. in the above result. They proved the following result

Theorem A. *Let M be a compact immersed surface of genus zero in $M^2(k) \times \mathbb{R}$. Assume that*

$$|dH| \leq g|Q^{(2,0)}|,$$

where $|dH|$ is the norm of the differential dH of the mean curvature H of M , and g is a continuous, nonnegative real function. Then $Q^{(2,0)}$ is identically zero, hence by [AR1], M is a CMC (constant mean curvature) embedded surface invariant by rotations in $M^2(k) \times \mathbb{R}$.

The goal of the present paper is to generalize Theorem A for immersed surfaces M in $\mathbb{E}^3(k, \tau)$, for $\tau \neq 0$.

For that, we first introduce the quadratic form

$$Q(X, Y) = 2(H + i\tau)\alpha(X, Y) - (k - 4\tau^2)\langle \xi, X \rangle \langle \xi, Y \rangle$$

for tangent vectors X, Y in M . The expression of the above form was inspired in a joint paper of Abresch and Rosenberg [AR2] in which they announce that the theorem of [AR1] (case $H = \text{const}$.) can be extended to surfaces immersed in $\mathbb{E}^3(k, \tau)$. As usual, we denote by $Q^{(2,0)}$ the $(2, 0)$ -component of Q in the complex structure of M determined by the induced metric. We prove

Theorem 1. *Let M be a compact surface of genus zero immersed in $\mathbb{E}^3(k, \tau)$ with mean curvature H . Assume that*

$$|dH| \leq g|Q^{(2,0)}|,$$

where g is a continuous nonnegative real function. Then $Q^{(2,0)}$ is identically zero and, by [AR2], M is a CMC surface invariant by rotations in $\mathbb{E}^3(k, \tau)$.

2 Preliminaries

Set $\theta = H + i\tau$, $c = k - 4\tau^2$ and write Q as

$$Q(X, Y) = 2\theta \alpha(X, Y) - c \langle \xi, X \rangle \langle \xi, Y \rangle.$$

The $(2, 0)$ -component of Q is

$$Q^{(2,0)} = \psi(z) dz dz.$$

Here $z = u + iv$, where (u, v) are isothermal parameters in M , i.e.,

$$\left\langle \frac{\partial}{\partial u}, \frac{\partial}{\partial u} \right\rangle = \left\langle \frac{\partial}{\partial v}, \frac{\partial}{\partial v} \right\rangle = \lambda^2, \quad \left\langle \frac{\partial}{\partial u}, \frac{\partial}{\partial v} \right\rangle = 0,$$

and

$$dz = \frac{1}{\sqrt{2}} (du + idv), \quad d\bar{z} = \frac{1}{\sqrt{2}} (du - idv).$$

Set

$$Z = \frac{1}{\sqrt{2}} \left(\frac{\partial}{\partial u} - i \frac{\partial}{\partial v} \right), \quad \bar{Z} = \frac{1}{\sqrt{2}} \left(\frac{\partial}{\partial u} + i \frac{\partial}{\partial v} \right),$$

so that

$$dz(Z) = 1 = d\bar{z}(\bar{Z}), \quad dz(\bar{Z}) = d\bar{z}(Z) = 0.$$

Notice also that

$$Q(Z, Z) = \psi(z) \quad \text{and} \quad \langle Z, \bar{Z} \rangle = \lambda^2, \quad \langle Z, Z \rangle = \langle \bar{Z}, \bar{Z} \rangle = 0.$$

We first prove the lemma below that will be used repeatedly in this section.

Lemma 1. *With the above notation*

$$\nabla_{\bar{Z}} Z = \nabla_Z \bar{Z} = 0,$$

where ∇ is the covariant derivative in M .

Proof. From the symmetry of the connexion we have

$$\nabla_{\bar{Z}} Z - \nabla_Z \bar{Z} = [Z, \bar{Z}].$$

A straightforward computation shows that, for any function f on M , $[Z, \bar{Z}](f) = 0$, so that $\nabla_{\bar{Z}}Z = \nabla_Z\bar{Z}$. Now set

$$\nabla_{\bar{Z}}Z = aZ + b\bar{Z} = \nabla_Z\bar{Z}.$$

Then, since $\langle Z, Z \rangle = 0$,

$$0 = \frac{1}{2} \bar{Z} \langle Z, Z \rangle = \langle \nabla_{\bar{Z}}Z, Z \rangle = b\lambda^2.$$

It follows that $b = 0$ and $\nabla_{\bar{Z}}Z = aZ$. Similarly, since $\langle \bar{Z}, \bar{Z} \rangle = 0$,

$$0 = \frac{1}{2} Z \langle \bar{Z}, \bar{Z} \rangle = \langle \nabla_Z\bar{Z}, \bar{Z} \rangle = a\lambda^2$$

so that $a = 0$ and $\nabla_{\bar{Z}}Z = \nabla_Z\bar{Z} = 0$. □

Next, we compute

$$\frac{d\psi}{d\bar{z}} = \bar{Z} Q(Z, Z) = \bar{Z}(2\theta \langle SZ, Z \rangle - c \langle \xi, Z \rangle^2),$$

where S is the shape operator corresponding to α .

Proposition 1. $\bar{Z} Q(Z, Z) = 2\bar{Z}(H)\alpha(Z, Z) + 2\theta\lambda^2 Z(H)$.

Proof.

$$\begin{aligned} \bar{Z} Q(Z, Z) &= 2\bar{Z}(\theta) \langle SZ, Z \rangle + 2\theta \langle \nabla_{\bar{Z}}(SZ), Z \rangle - 2c \langle \xi, Z \rangle \langle \bar{\nabla}_{\bar{Z}}\xi, Z \rangle \\ &\quad - 2c \langle \xi, Z \rangle \langle \xi, \bar{\nabla}_{\bar{Z}}Z \rangle, \end{aligned} \tag{1}$$

where we have used that $\nabla_{\bar{Z}}Z = 0$. In the Lemmas below, we compute separately $\langle \nabla_{\bar{Z}}(SZ), Z \rangle$, $\langle \bar{\nabla}_{\bar{Z}}\xi, Z \rangle$ and $\langle \xi, \bar{\nabla}_{\bar{Z}}Z \rangle$.

Lemma 2. $\langle \nabla_{\bar{Z}}(SZ), Z \rangle = \langle \nabla_Z(S\bar{Z}), Z \rangle + c\lambda^2 \langle \xi, N \rangle \langle \xi, Z \rangle$.

Proof. By using that $\nabla_{\bar{Z}}Z = 0$ and Codazzi equation, we obtain

$$\begin{aligned} \nabla_{\bar{Z}}(SZ) &= (\nabla_{\bar{Z}}S)(Z) + S(\nabla_{\bar{Z}}\bar{Z}) \\ &= (\nabla_ZS)(\bar{Z}) + \tilde{R}(Z, \bar{Z})N \\ &= (\nabla_ZS)\bar{Z} + c \langle N, \xi \rangle (\langle Z, \xi \rangle \bar{Z} - \langle \bar{Z}, \xi \rangle Z), \end{aligned}$$

where \tilde{R} is the curvature of $\mathbb{E}^3(k, \tau)$ and we have used Corollary 3.2 of Daniel [D]. Finally, since $\langle Z, Z \rangle = 0$, we conclude that

$$\bar{Z}(SZ), Z \quad \nabla_Z(S\bar{Z}), Z + c \langle N, \xi \rangle \langle Z, \xi \rangle \lambda^2. \quad \square$$

Lemma 3. $\langle \bar{\nabla}_Z \xi, Z \rangle = i \tau \lambda^2 \langle \xi, N \rangle$, where N is the normal to the surface M .

Proof. By using ([D], proof of the Proposition 3.2) we obtain

$$\bar{\nabla}_Z \xi = \tau \xi \times \bar{Z} = \tau (\langle J\bar{Z}, \xi \rangle N - \langle \xi, N \rangle J\bar{Z}),$$

where J is the complex multiplication by i . Thus

$$\langle \bar{\nabla}_Z \xi, Z \rangle = -\tau \langle \xi, N \rangle i \lambda^2. \quad \square$$

Lemma 4. $\langle \xi, \bar{\nabla}_Z Z \rangle = \lambda^2 H \langle \xi, N \rangle$.

Proof. $\bar{\nabla}_Z Z = \nabla_Z Z + \alpha(\bar{Z}, Z)N$.

Since $\nabla_Z Z = 0$ and $\alpha(\bar{Z}, Z) = \lambda^2 H$. (See the proof of Lemma 2 in [AdCT]), we conclude that

$$\langle \xi, \bar{\nabla}_Z Z \rangle = \lambda^2 H \langle \xi, N \rangle. \quad \square$$

Putting Lemmas 2, 3 and 4 in the expression (1) of $\bar{Z}Q(Z, Z)$, we obtain

$$\begin{aligned} \bar{Z}Q(Z, Z) &= 2\bar{Z}(H)\alpha(Z, Z) + 2\theta \langle \nabla_Z(S\bar{Z}), Z \rangle + 2\theta c\lambda^2 \langle N, \xi \rangle \langle Z, \xi \rangle \\ &\quad - 2ci\tau\lambda^2 \langle \xi, Z \rangle \langle \xi, N \rangle - 2c\lambda^2 H \langle \xi, N \rangle \langle \xi, Z \rangle. \end{aligned}$$

Since $\theta = H + i\tau$, the two last terms of the above sum cancel out with the third term. Thus

$$\bar{Z}Q(Z, Z) = 2\bar{Z}(H)\alpha(Z, Z) + 2\theta \langle \nabla_Z(S\bar{Z}), Z \rangle. \quad (2)$$

To conclude the proof of Proposition 1, we still need some information on the term $\langle \nabla_Z(S\bar{Z}), Z \rangle$.

Lemma 5. $\langle \nabla_Z(S\bar{Z}), Z \rangle = \lambda^2 Z(H)$.

Proof. We first claim that

$$\nabla_Z Z = \frac{Z(\lambda^2)}{\lambda^2} Z.$$

To see that, set $\nabla_Z Z = aZ + b\bar{Z}$. Then

$$\langle \nabla_Z Z, Z \rangle = b\lambda^2 = \frac{1}{2} Z \langle Z, Z \rangle = 0.$$

It follows that $b = 0$, hence $\nabla_Z Z = aZ$. But

$$\langle \nabla_Z Z, \bar{Z} \rangle = Z \langle Z, \bar{Z} \rangle = Z(\lambda^2) = a \langle Z, \bar{Z} \rangle.$$

It follows that $a = \frac{Z(\lambda^2)}{\lambda^2}$, and this proves our claim.

Now, notice that

$$Z(\lambda^2 H) = Z(\langle S\bar{Z}, Z \rangle) = \langle \nabla_Z(S\bar{Z}), Z \rangle + \langle S\bar{Z}, \nabla_Z Z \rangle.$$

Thus

$$\begin{aligned} \langle \nabla_Z(S\bar{Z}), Z \rangle &= Z(\lambda^2)H + \lambda^2 Z(H) - \langle S\bar{Z}, \nabla_Z Z \rangle \\ &= Z(\lambda^2)H + \lambda^2 Z(H) - \langle S\bar{Z}, Z \rangle \frac{Z(\lambda^2)}{\lambda^2} \\ &= \lambda^2 Z(H), \end{aligned}$$

since $\langle S\bar{Z}, Z \rangle = \lambda^2 H$. □

By using Lemma 5 in Equation (2) we conclude the proof of Proposition 1.

Proof of Theorem 1. By Proposition 1, we have

$$\begin{aligned} |\bar{Z} Q(Z, Z)| &= |2\bar{Z}(H)\alpha(Z, Z) + 2\theta\lambda^2 Z(H)| \\ &\leq |dH| |\lambda| |2\alpha(Z, Z) + 2\theta\lambda^2|, \end{aligned}$$

where we have used that $|\bar{Z}(H)| = |dH(\bar{Z})| \leq |dH| |\bar{Z}|$ and $|Z(H)| \leq |dH| |\lambda|$. By hypothesis, $|dH| \leq g|Q^{(2,0)}|$, for a continuous $g \geq 0$. Thus

$$\left| \frac{d\psi}{d\bar{z}} \right| = |\bar{Z} Q(Z, Z)| \leq h|Q^{(2,0)}| = h|\psi(z)|, \quad (3)$$

where

$$h = g|\lambda| (|\alpha(Z, Z)| + 2\lambda^2|H + i\tau|),$$

i.e., h is a continuous nonnegative function on M . We now use the Main Lemma of [AdCT] which states that if a function $\psi(z)$ satisfies the inequality (3) in a neighborhood U of a zero z_0 of ψ , then either $\psi \equiv 0$ in a neighborhood $V \subset U$ of z_0 or, for all z in V ,

$$\psi(z) = (z - z_0)^m f_m(z), \quad m \geq 1, \quad f_m(z_0) \neq 0. \quad (4)$$

From that we can conclude the proof of Theorem 1 in the same way as in ([AdCT] end of section 2). For completeness, we summarize the argument here.

By the Main Lemma, either $Q^{(2,0)} \equiv 0$, hence by [AR2], M is a surface of revolution, or $Q^{(2,0)}$ has a finite number of zeroes. We show that this case leads to a contradiction. Indeed, the equation $\text{Im}[Q(Z, Z)dz^2] = 0$ gives rise to two fields of directions on M whose singularities are the zeroes of $Q(Z, Z)$. The index of any of these fields at the singular point is equal to $-m/2$, where m is the order of the zero that appears in Equation (4). Since M has genus zero, the sum of the indices of this field of directions, by Poincaré Theorem ([H], Chapter III, sect. 2), is two. This is a contradiction, thereby concluding the proof of Theorem 1.

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