

Mini-course in Maceio on embedded constant mean curvature surfaces in \mathbb{R}^3

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Based on joint work with Giuseppe Tinaglia.

Some preliminary papers on the lecture material can be found on Tinaglia's web page at Kings College London.

Outline of 3 lectures

- 1 Lecture 1: Background material, statements of the main results.
- 2 Lecture 2: Proof of extrinsic curvature estimates for H -disks.
- 3 Lecture 3: Applications:
 - 1 Intrinsic curvature and radius estimates for H -disks.
 - 2 Chord-arc results and 1 -sided curvature estimates for H -disks.
 - 3 Curvature estimates for H -annuli.
 - 4 Classification of 0 and 1 -connected H -surfaces, $H > 0$.

Definition

- An continuous map $f: X \rightarrow Y$ between topological spaces is **proper**, if for each compact set $\Delta \subset Y$, $f^{-1}(\Delta)$ is compact in X .
- An embedded surface $M \subset \mathbb{R}^3$ is **proper** if its inclusion map is proper.

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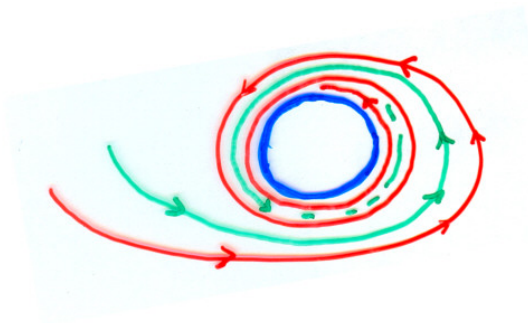
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Remark

A smooth embedded noncompact surface $M \subset \mathbb{R}^3$ that is **not** proper must have accumulation points, i.e., \exists a sequence of points $\mathbf{p}_n \in M$ such that $\lim_{n \rightarrow \infty} \mathbf{p}_n = \mathbf{p} \in \mathbb{R}^3$, but this sequence fails to converge in the intrinsic Riemannian metric space structure on M .

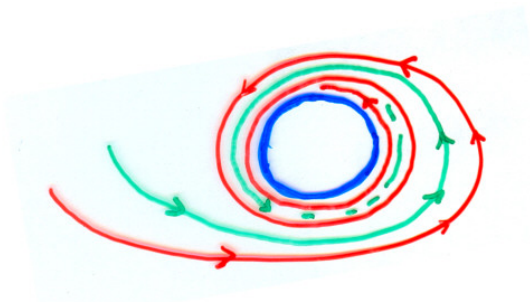
Example (Non-proper curves in \mathbf{R}^2)

Below is a picture of the union \mathcal{L} of 2 infinite **non-proper** **green** and **red** spirals in \mathbf{R}^2 with the blue circle S^1 as its accumulation or limit set.



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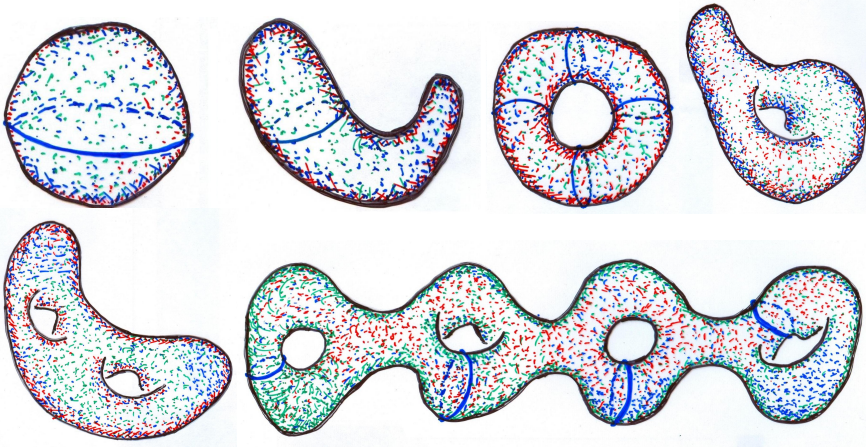


Example (Non-proper embedded surfaces in \mathbb{R}^3)

The cross product $(\mathcal{L} \times \mathbb{R}) \subset \mathbb{R}^2 \times \mathbb{R} = \mathbb{R}^3$ corresponds to 2 non-proper embedded topological planes that spiral into the cylinder $(S^1 \times \mathbb{R}) \subset \mathbb{R}^3$.

Theorem (Classification of compact surfaces in \mathbb{R}^3)

An embedded compact surface M in \mathbb{R}^3 is topologically equivalent to a sphere S with g -handles attached. The integer $g = \text{genus}(M) = \max \#$ of pairwise disjoint simple closed curves which do not separate M .



Definition

- The **genus** g of a surface M is the maximum number of pairwise disjoint simple closed curves which do not separate the surface; note that if M is a sphere with g -handles attached, then it has genus g .
- A surface M has **finite topology** if it is topologically equivalent to a compact surface with a finite subset of points $E = \{p_1, p_2, \dots, p_n\}$ removed; E is called the set of **ends** of M .
- A surface $M \subset \mathbb{R}^3$ is a **planar domain** if it is topologically equivalent to a connected open set of the plane \mathbb{R}^2 .
- An embedded surface $M \subset \mathbb{R}^3$ is **complete** if with respect to its Riemannian distance function, it is a complete metric space.

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Remark (Properness versus Completeness)

Every properly immersed surface $M \looparrowright \mathbb{R}^3$ is complete, since metric spaces where every closed ball $\overline{B}_M(\mathbf{p}, 1) \subset M$ of radius 1 is compact are always complete.

Theorem (Classification of noncompact genus $g = 0$ surfaces)

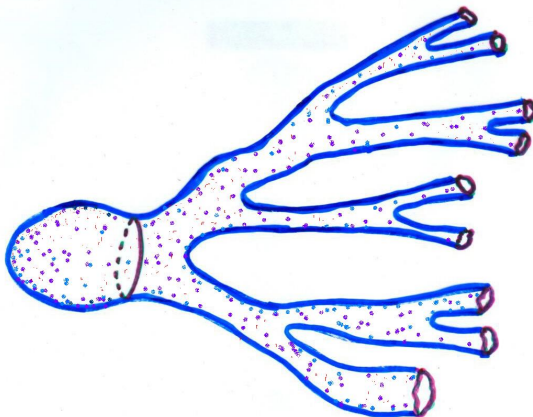
View the sphere S^2 as $R^2 \cup \{\infty\}$.

- A connected noncompact surface M_E of **genus** = **0** can be parameterized by $S^2 - E$, where $E \subset S^1 \subset S^2$ is a totally disconnected compact set called the **space of ends** of M_E . Hence:

Noncompact genus 0 surfaces are planar domains.

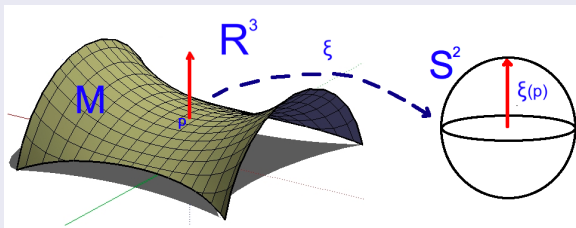
- Two planar domains $M_{E(1)}$, $M_{E(2)}$ are homeomorphic \Leftrightarrow their spaces of ends $E(1)$, $E(2)$ are homeomorphic.

A proper $g = 0$ surface M_E with $E =$ a Cantor set.



S^2 - Cantor set

Introduction to the theory of CMC surfaces.



Let M be an oriented surface in \mathbb{R}^3 , let ξ be the unit vector field normal to M :

$$A_p = -d\xi: T_p M \rightarrow T_{\xi(p)} S^2 \simeq T_p M$$

is the **shape operator** of M . A_p is symmetric linear transformation.

Introduction to the theory of CMC surfaces.

Definition

- The eigenvalues k_1, k_2 of \mathbf{A}_p are the **principal curvatures** of \mathbf{M} at \mathbf{p} .
- $\mathbf{K} = \det(\mathbf{A}) = k_1 k_2$ is the **Gauss curvature** function.
- $\mathbf{H} = \frac{1}{2} \operatorname{tr}(\mathbf{A}) = \frac{k_1 + k_2}{2}$ is the **mean curvature** function.
- $|\mathbf{A}| = \sqrt{k_1^2 + k_2^2}$ is the **norm of the shape operator**.

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Gauss equation

$$4\mathbf{H}^2 = |\mathbf{A}|^2 + 2\mathbf{K} \quad (\mathbf{K} = \text{Gaussian curvature})$$

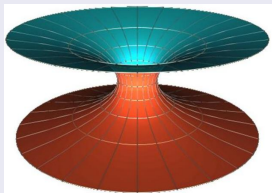
In particular:

- 1 When $\mathbf{H}(\mathbf{p}) = 0$, then $\mathbf{K}(\mathbf{p}) \leq 0$.
- 2 When $\mathbf{H}(\mathbf{p}) = 1$, then $\mathbf{K}(\mathbf{p}) = 2 - \frac{1}{2}|\mathbf{A}|(\mathbf{p})$, and so estimates for $|\mathbf{A}|$ give estimates on the Gaussian curvature when \mathbf{M} has constant mean curvature **1**.

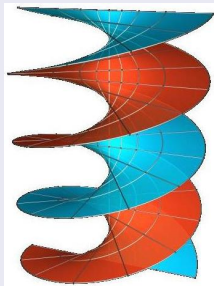
Part 2: Introduction to the theory of H-surfaces.

Definition

An **H**-surface **M** is a **minimal surface** $\iff \mathbf{H} \equiv 0 \iff \mathbf{M}$ is a critical point for the area functional under compactly supported variations.



• Catenoid

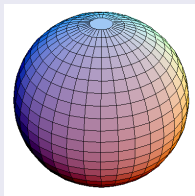


• Helicoid

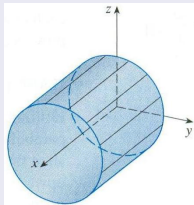
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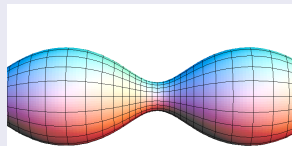
M is a **H-surface** \iff M is a critical point for the area functional under compactly supported variations **preserving the volume**.



• Sphere



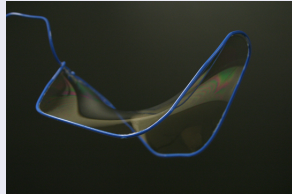
• Cylinder



• Delaunay surfaces

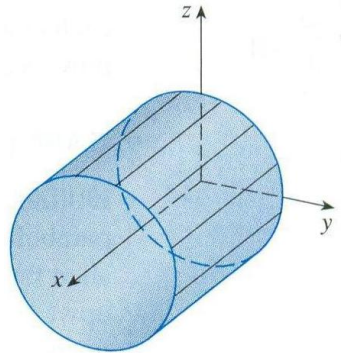
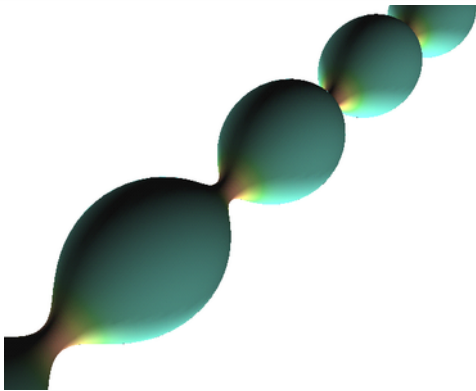
H-surfaces in nature.

Soap films are minimal surfaces.

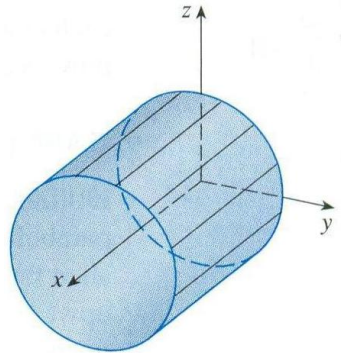
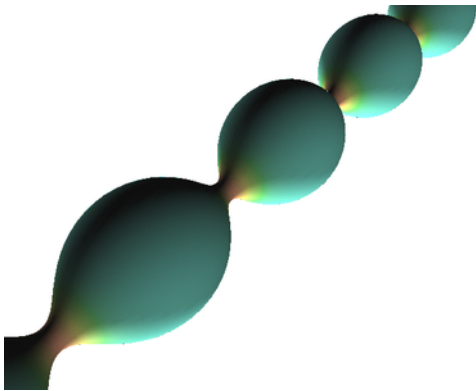


Soap bubbles are nonzero H-surfaces.

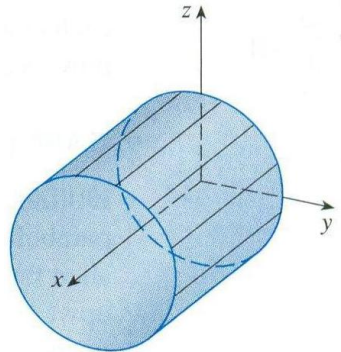
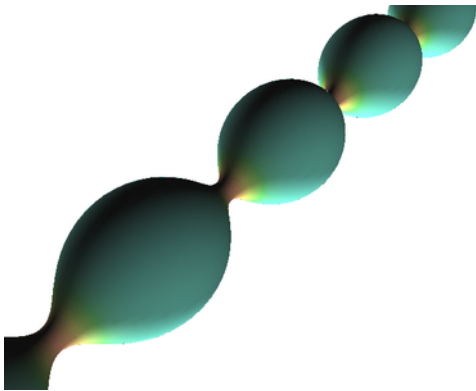




- In 1845, **Delaunay** discovered and classified the surfaces of revolution with constant mean curvature $H = 1$.



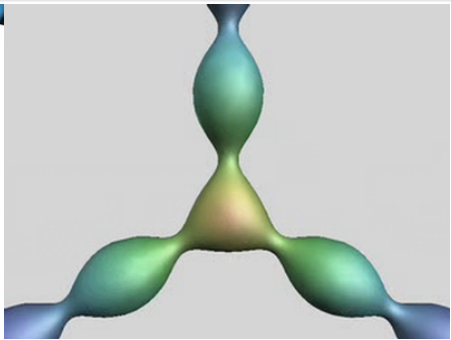
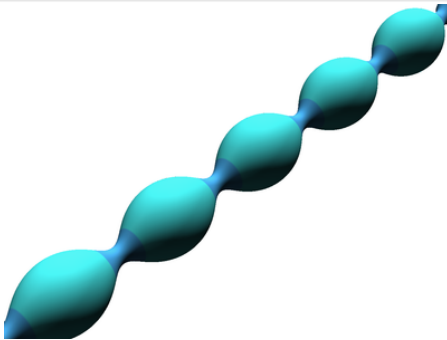
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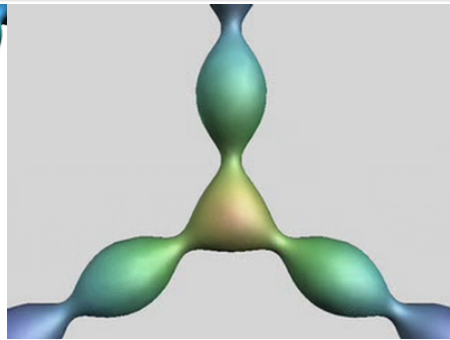
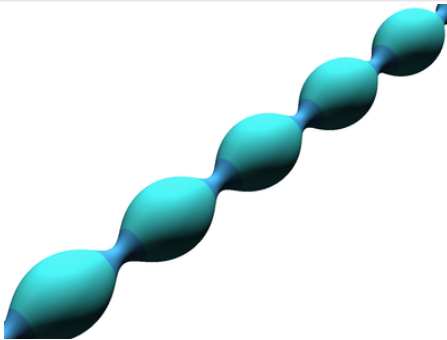
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- The Sphere **S** of radius 1 and the Cylinder **C** of radius $\frac{1}{2}$ were already known.
- He wrote down a 1-parameter family \mathcal{D}_t , called **unduloids** or **Delaunay surfaces**, where

$$\lim_{t \rightarrow 0} \mathcal{D}_t = \mathbf{S}$$

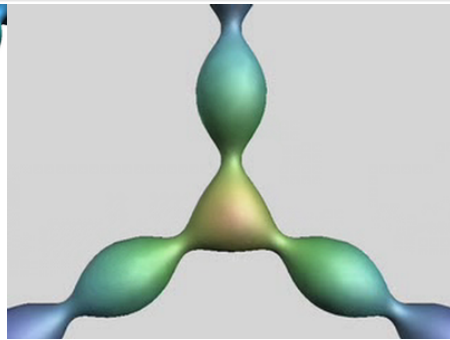
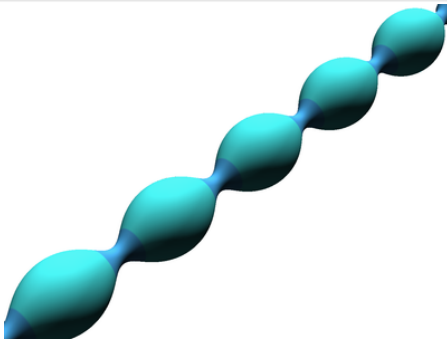
$$\lim_{t \rightarrow \infty} \mathcal{D}_t = \mathbf{C}.$$



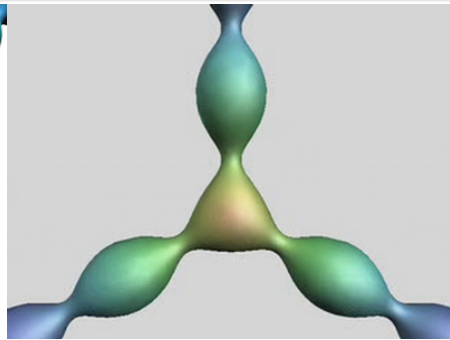
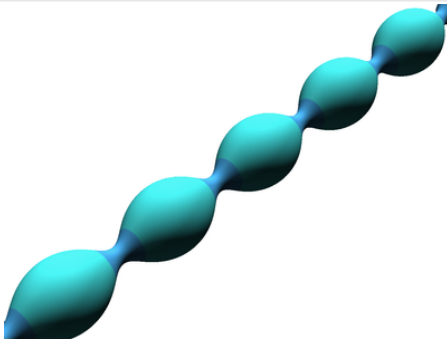
- A different Delaunay surface and an **H**-surface called a **CMC** Trinoid or just **Trinoid**.



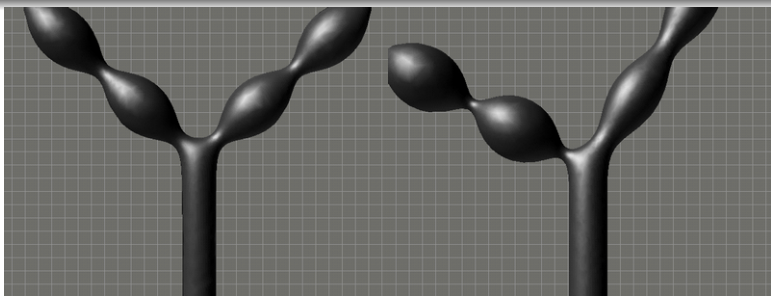
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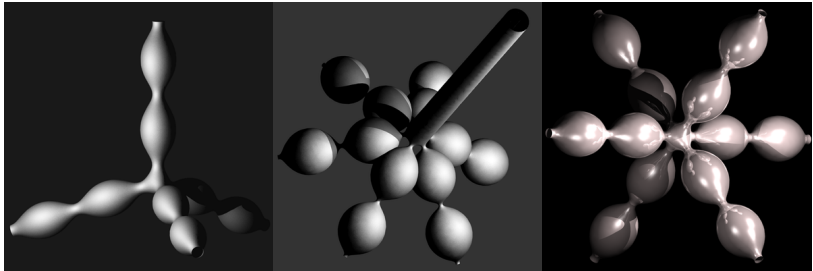
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- A Trinoid is topologically a planar domain with three ends, each end is topologically an annulus, **asymptotic** to the end of a cylinder or to the end of some Delaunay surface.



2 Trinoids each with 1 cylindrical and 2 Delaunay-type ends.

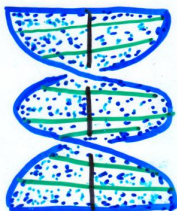


n -noids with the middle one having 1 cylindrical-type end.

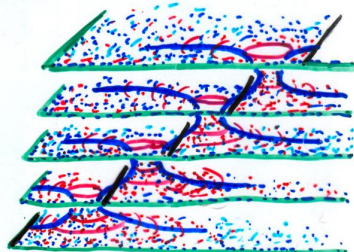
Moduli space of genus-0 minimal examples - Meeks, Pérez & Ros



Catenoid



Helicoid



Riemann



plane

MODULI SPACE

CATENOID

$\mathcal{R}_t =$ Riemann Examples

HELICOID

Definition (Smyth and Tinaglia)

- Let γ be a piecewise-smooth 1-cycle in an \mathbf{H} -surface \mathbf{M} .
- The **flux** of γ is $\int_{\gamma} (\mathbf{H}\gamma + \xi) \times \dot{\gamma}$, where ξ is the unit normal to \mathbf{M} along γ .
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Remark (Application of flux)

If $\mathbf{M}_n \subset \mathbf{R}^3$ is a sequence of \mathbf{H}_n -disks that converge smoothly to a non-flat properly embedded minimal surface \mathbf{M}_{∞} , then \mathbf{M}_{∞} is a helicoid!

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Proof.

- By curve liftings, the limit surface surface must have genus $\mathbf{0}$.
- By the classification of properly embedded minimal planar domains, \mathbf{M}_{∞} is a helicoid, a catenoid or a Riemann minimal example.
- The fluxes of the \mathbf{M}_n are $\mathbf{0}$, so the flux of \mathbf{M}_{∞} is $\mathbf{0}$.
- But flux of circles on catenoids or Riemann examples $\neq \mathbf{0}$. □

Motivating question for the Main Results.

Do there exist complete, embedded \mathbf{M} in \mathbf{R}^3 having constant mean curvature $\mathbf{H} \neq \mathbf{0}$ which are topologically the plane \mathbf{R}^2 ?

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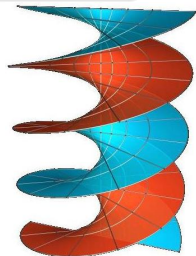
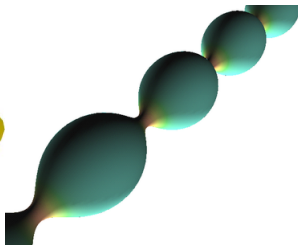
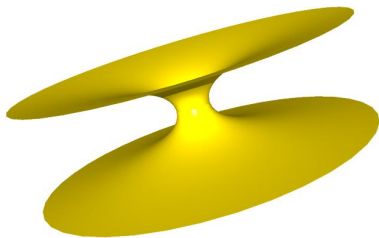
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- More generally, the work of **Meeks, Meeks-Rosenberg, Colding-Minicozzi, Collin, Lopez-Ros, Korevaar, Kusner, Solomon**, the next theorem by **Meeks-Tinaglia** completes the **classification** of complete, embedded H -surfaces with genus **0** and **0, 1** or **2** ends.

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- They are:
Planes, spheres, catenoids, unduloids, helicoids.



Part 3: Summary of the Main Results

Theorem (Radius Estimates for \mathbf{H} -Disks, Meeks-Tinaglia 2014)

$\exists R_0 \geq \pi$ such that every embedded $\mathbf{1}$ -disk in \mathbf{R}^3 has radius $< R_0$.

Part 3: Summary of the Main Results

Theorem (Radius Estimates for H -Disks, Meeks-Tinaglia 2014)

$\exists R_0 \geq \pi$ such that every embedded 1 -disk in \mathbb{R}^3 has radius $< R_0$.

Corollary (Meeks-Tinaglia 2014)

A complete simply connected H -surface embedded in \mathbb{R}^3 with $H > 0$ is a round sphere.

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Corollary (Meeks-Tinaglia 2014)

A complete simply connected \mathbf{H} -surface embedded in \mathbf{R}^3 with $\mathbf{H} > 0$ is a round sphere.

Theorem (Curvature Estimates for \mathbf{H} -Disks, Meeks-Tinaglia 2014)

Fix $\varepsilon > 0$ and $\mathbf{H} = 1$. $\exists C \geq 1$ such that for every embedded $\mathbf{1}$ -disk $\mathbf{D} \subset \mathbf{R}^3$ and every $p \in \mathbf{D}$ with $\mathbf{dist}_{\mathbf{D}}(p, \partial\mathbf{D}) \geq \varepsilon$,

$$|\mathbf{A}_{\mathbf{D}}|(p) \leq C.$$

Theorem (One-sided curvature estimate for \mathbf{H} -disks, Meeks-Tinaglia)

There exist $\varepsilon \in (0, \frac{1}{2})$ and $C \geq 2\sqrt{2}$ such that for any $R > 0$, the following holds. Let Σ be an \mathbf{H} -disk such that

$$\Sigma \cap \mathbb{B}(R) \cap \{x_3 = 0\} = \emptyset \quad \text{and} \quad \partial\Sigma \cap \mathbb{B}(R) \cap \{x_3 > 0\} = \emptyset.$$

Then:

$$\sup_{x \in \Sigma \cap \mathbb{B}(\varepsilon R) \cap \{x_3 > 0\}} |\mathbf{A}_\Sigma|(x) \leq \frac{C}{R}. \quad (1)$$

In particular, if $\Sigma \cap \mathbb{B}(\varepsilon R) \cap \{x_3 > 0\} \neq \emptyset$, then $\mathbf{H} \leq \frac{C}{R}$.

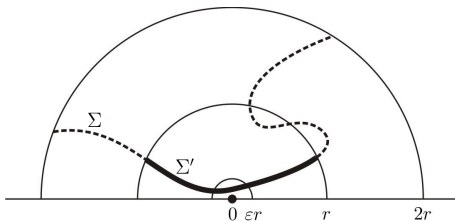


Figure: The one-sided curvature estimate.

Theorem (One-side Curvature Estimate, Colding-Minicozzi)

- There exists an $\varepsilon > 0$ such that the following holds.
- Given $r > 0$ and an embedded minimal disk $\Sigma \subset \mathbb{B}(2r) \cap \{x_3 > 0\}$ with $\partial\Sigma \subset \partial\mathbb{B}(2r)$, then for any component Σ' of $\Sigma \cap \mathbb{B}(r)$ which intersects $\mathbb{B}(\varepsilon r)$,

$$r^2 \sup_{\Sigma'} |K_{\Sigma}| \leq 1. \quad (2)$$

Theorem (Chord-Arc Theorem, Meeks-Tinaglia)

There exists a positive constant C such that if $\Sigma \subset \mathbf{R}^3$ is an \mathbf{H} -disk, $B_{\Sigma}(\vec{0}, CR) \subset \Sigma - \partial\Sigma$ and $\sup_{B_{\Sigma}(\vec{0}, r_0)} |\mathbf{A}_{\Sigma}| \geq \frac{1}{r_0}$ where $R > r_0$, then for $x \in B_{\Sigma}(\vec{0}, R)$,

$$\frac{1}{6} \operatorname{dist}_{\Sigma}(x, \vec{0}) < |x| + r_0. \quad (3)$$

- This theorem generalizes a similar result by Colding-Minicozzi for $\mathbf{H} = 0$.
- The above theorem implies that a complete simply connected \mathbf{H} -surface embedded in \mathbf{R}^3 is proper!!

Theoretical results on complete embedded H-surfaces

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- In 1989, **Korevaar, Kusner** and **Solomon** proved that each annular end of M is **asymptotic** to the end of a Delaunay surface. They also showed that if M has finite topology and 2 ends, then it is a Delaunay surface.

Theoretical results on complete embedded H-surfaces

Let M be an H -surface properly embedded in \mathbb{R}^3 , $H > 0$.

- In 1951, **Hopf** proved that if M is compact and immersed (not necessarily embedded) of genus 0 , then it is a round sphere.
- In 1956, **Alexandrov** proved that if M is compact, then it is a round sphere.
- In 1988, **Meeks** proved that M cannot have finite topology and 1 end.
- In 1989, **Korevaar, Kusner** and **Solomon** proved that each annular end of M is **asymptotic** to the end of a Delaunay surface. They also showed that if M has finite topology and 2 ends, then it is a Delaunay surface.
- Recently **Meeks** and **Tinaglia** proved that if $\Sigma \subset \mathbb{R}^3$ is a complete, embedded H -surface with finite topology, then Σ is properly embedded. (Proved for $H = 0$ by **Colding-Minicozzi, 2008**)

Definition (Injectivity Radius)

- Given a Riemannian surface M , the injectivity radius function $I_M: M \rightarrow (0, \infty]$ is defined by: $I_M(\mathbf{p}) = \sup\{R > 0 \mid \exp_{\mathbf{p}}: B(R) \subset T_{\mathbf{p}}M \rightarrow M \text{ is a diffeomorphism.}\}$
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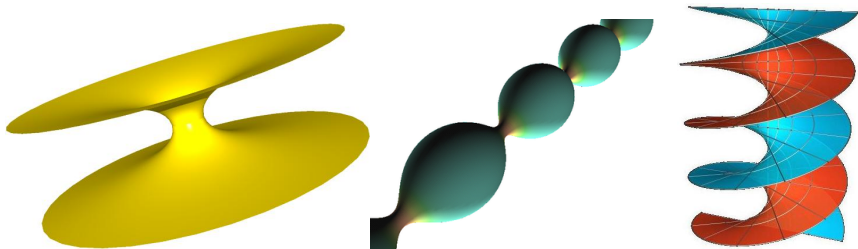
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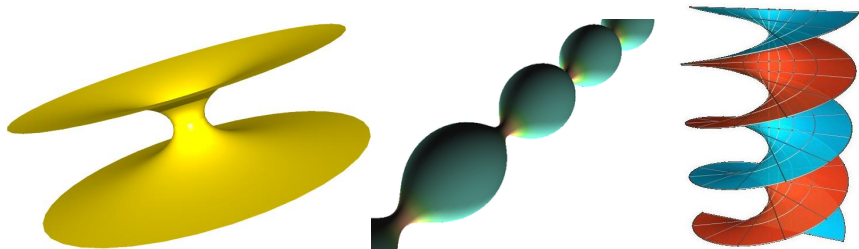
Theorem (Meeks-Tinaglia, based on previous work of Colding-Minicozzi & Meeks-Rosenberg)

- Complete embedded H -surfaces $M \subset \mathbb{R}^3$ with finite topology have positive injectivity radius.
- Let $M \subset \mathbb{R}^3$ be a complete, connected embedded H -surface with $H > 0$ and positive injectivity radius. Then M has bounded second fundamental form and it is properly embedded in \mathbb{R}^3 .

- This theorem by **Meeks-Tinaglia** and work of **Meeks-Rosenberg**, **Colding-Minicozzi**, **Collin**, **Lopez-Ros** when $H = 0$, and **Meeks** and **Korevaar-Kusner-Solomon** when $H \neq 0$, completes the **classification** of complete, embedded H -surfaces of genus **0** with **0**, **1** or **2** ends.
- They are **planes**, **spheres**, **catenoids**, **unduloids**, **helicoids**.



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Remark

One **Main Objective** of this course is to present the theory behind this classification for the special case where $H > 0$.